

\mathcal{A} -quasiconvexity, function spaces & regularity

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partly based on joint work with

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Universität
Konstanz



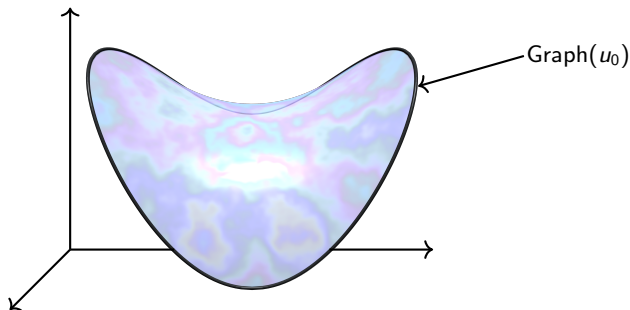
Function Space Seminar, Prague, Jan 06, 2022

Minimal Surfaces

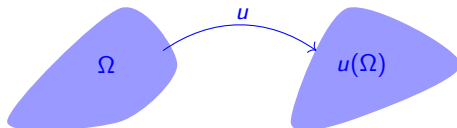
The classical minimal surface problem reads as

$$\text{minimise } \mathcal{F}[u] := \int_{\Omega} \sqrt{1 + |\nabla u|^2} \, dx \quad \text{subject to } u|_{\partial\Omega} = u_0.$$

- Graphs of minimisers yield *minimal surface* with 'boundary datum' u_0 .



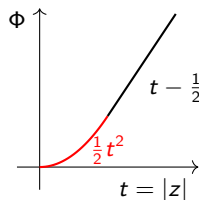
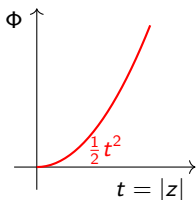
Elasticity and plasticity



- Symmetric gradient: $\varepsilon(u) := \frac{1}{2}(Du + Du^T)$
- Trace-free symmetric gradient: $\varepsilon^D(u) := \varepsilon(u) - \frac{1}{n} \operatorname{div}(u) E_n$

$$\text{minimise } \mathcal{F}[u] := \int_{\Omega} \Phi(|\varepsilon^D(u)|) \, dx + \frac{1}{2} \int_{\Omega} |\operatorname{div}(u)|^2 \, dx - \int_{\Omega} F \cdot u \, dx$$

subject to suitable side constraints (forces, tensions)



A unifying framework I

Let $\Omega \subset \mathbb{R}^n$ be a bounded Lipschitz domain with $\mathbb{A}_\alpha \in \mathcal{L}(V; W)$,

$$\mathbb{A} = \sum_{|\alpha|=k} \mathbb{A}_\alpha \partial^\alpha : v \mapsto \sum_{|\alpha|=k} \mathbb{A}_\alpha \partial^\alpha v, \quad v: \Omega \rightarrow V$$

a vectorial differential operator. We aim to minimise

$$\mathcal{F}[u] := \int_{\Omega} f(\mathbb{A}u) \, dx \quad \text{over suitable maps } u \text{ with } u|_{\partial\Omega} = u_0,$$

where $u_0: \Omega \rightarrow V$ is a suitable Dirichlet datum and f has $1 \leq p < \infty$ **growth**:

$$|f(z)| \leq c(1 + |z|^p) \quad \text{for all } z \in W.$$

Example (The symmetric gradient)

$$V = \mathbb{R}^n, \, W = \mathbb{R}_{\text{sym}}^{n \times n}, \, \mathbb{A}u := \varepsilon(u) := \frac{1}{2}(Du + Du^\top)$$

Example (The trace-free symmetric gradient)

$$V = \mathbb{R}^n, \, W = \mathbb{R}_{\text{tf,sym}}^{n \times n}, \, \mathbb{A}u := \varepsilon^D(u) := \varepsilon(u) - \frac{1}{n} \operatorname{div}(u) E_n$$

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A unifying framework II

$$\mathcal{F}[u] := \int_{\Omega} f(\mathbb{A}u) \, dx, \quad |f(z)| \leq c(1 + |z|^p)$$

- 1 $|\mathbb{A}u|^p$ should be integrable and u should attain the right boundary values
 \rightsquigarrow denote this class \mathcal{X}_p .
- 2 (v_i) in \mathcal{X}_p with $\mathcal{F}[v_i] \rightarrow \inf_{\mathcal{X}_p} \mathcal{F}$
- 3 Hope for boundedness of (v_i) in \mathcal{X}_p to extract a suitably convergent subsequence in a weak sense: $v_{i(j)} \rightsquigarrow v$
- 4 Sequential LSC for ' \rightsquigarrow ': $\mathcal{F}[v] \leq \liminf_{j \rightarrow \infty} \mathcal{F}[v_{i(j)}]$

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Reasonable:

$$W^{\mathbb{A},p}(\Omega) := \{u : \|u\|_{L^p(\Omega)} + \|\mathbb{A}u\|_{L^p(\Omega)} < \infty\}$$

Natural question: When do we have

$$W^{\mathbb{A},p}(\Omega) \simeq W^{k,p}(\Omega; V)?$$

Depends on \mathbb{A} and whether $1 < p < \infty$ or $p = 1$!

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Requires a generalisation of the

Quasiconvexity á la Morrey: $f: \mathbb{R}^{N \times n} \rightarrow \mathbb{R}$ continuous is called **quasiconvex** if

$$f(z) \leq \int_{(0,1)^n} f(z + \nabla \varphi) \, dx \quad \forall z \in \mathbb{R}^{N \times n}, \varphi \in C_c^\infty((0,1)^n; \mathbb{R}^N).$$

\longrightarrow will lead us to \mathcal{A} -quasiconvexity a la Fonseca & Müller

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Existence of minima



What can we say about their regularity?

Plan of the talk

Function spaces, harmonic analysis
and boundary behaviour of maps



Coercivity and LSC:
 p -strong \mathcal{A} -quasiconvexity



$C^{1,\alpha}$ -partial regularity of minimisers

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\mathbb{A} versus ∇^k – Calderón-Zygmund & Ornstein

Theorem (Korn versus Ornstein)

*In general, the inequality $\|\nabla^k u\|_{L^p} \leq c \|\mathbb{A}u\|_{L^p}$ holds for all $u \in C_c^\infty(\mathbb{R}^n; V)$ if and only if \mathbb{A} is elliptic and $1 < p < \infty$ – but **not for $p = 1$** .*

- We call \mathbb{A} **elliptic** \Leftrightarrow

$$\forall \xi \in \mathbb{R}^n \setminus \{0\}: \quad \mathbb{A}[\xi] := \sum_{|\alpha|=k} \xi^\alpha \mathbb{A}_\alpha: V \rightarrow W \text{ is injective}$$

- Write for $u \in C_c^\infty(\mathbb{R}^n; V)$ and $|\alpha| = k$:

$$\partial^\alpha u = c_n \mathcal{F}^{-1} \left(\underbrace{\xi^\alpha (\mathbb{A}[\xi]^* \mathbb{A}[\xi])^{-1} \mathbb{A}[\xi]^*}_{=m_\alpha(\xi)} \mathcal{F}[\mathbb{A}u] \right)$$

$\longrightarrow m_\alpha$ belongs to $C^\infty(\mathbb{R}^n \setminus \{0\}; \mathcal{L}(W; V))$ and is homogeneous of degree zero.

\longrightarrow Apply **Theorem of Mihlin-Hörmander/Calderón-Zygmund**.

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What survives? – Strengthening ellipticity

- Sobolev inequality:**

Van Schaftingen (JEMS, '13), based on Bourgain & Brezis (JAMS, '07):

$$\|u\|_{L^{\frac{n}{n-1}}(\mathbb{R}^n)} \lesssim \|\mathbb{A}u\|_{L^1(\mathbb{R}^n)} \text{ for } u \in C_c^\infty(\mathbb{R}^n; V)$$

$$\iff \mathbb{A} \text{ elliptic and } \bigcap_{\xi \in \mathbb{R}^n \setminus \{0\}} \mathbb{A}[\xi](V) = \{0\} \text{ (cancelling)}$$

- Trace inequalities?**

Example (The trace-free symmetric gradient)

The operator $\varepsilon^D(u) := \varepsilon(u) - \frac{1}{n} \operatorname{div}(u) E_n$

- $n = 2$: elliptic, but:

$$\varepsilon^D(u) \stackrel{!}{=} 0 \implies \begin{cases} \partial_1 u_1 &= \partial_2 u_2 \\ \partial_2 u_1 &= -\partial_1 u_2 \end{cases} \quad \text{Cauchy-Riemann!}$$

$f: \mathbb{D} \ni z \mapsto \frac{1}{z-1} \in \mathbb{C}$ holomorphic and $\int_{\partial \mathbb{D}} |f| d\mathcal{H}^1 = +\infty$.

- $n \geq 3$: $\ker(\varepsilon^D) = \{\text{Killing fields}\} \subset \mathcal{P}_2(\mathbb{R}^n; \mathbb{R}^n)$

Traces and boundary behaviour

Theorem (Breit, Diening, FXG, APDE '20 + Diening & FXG '21)

The following are equivalent for a k -th order operator \mathbb{A} and $1 \leq p < \infty$:

- ① \mathbb{A} is \mathbb{C} -elliptic, so

$$\mathbb{A}[\xi]: V + iV \rightarrow W + iW \quad \text{is injective for all } \xi \in \mathbb{C}^n \setminus \{0\}.$$

- ② For all open, bounded and smooth $\Omega \subset \mathbb{R}^n$ there holds

$$\mathrm{Tr}_{\partial\Omega}(W^{k,p}(\Omega; V)) = \mathrm{Tr}_{\partial\Omega}(W^{\mathbb{A},p}(\Omega))$$

- hinges on the Hilbert Nullstellensatz from algebraic geometry

$$u(x) = \Pi u(x) + \int_{\mathbb{B}} K_{\mathbb{A}}(x-y) \mathbb{A}u(y) dy \quad \Rightarrow \quad \ker(\mathbb{A}) \subset \mathcal{P}_m(\mathbb{R}^n; \mathbb{R}^N)$$

- \mathbb{C} -ellipticity is equivalent to $\ker(\mathbb{A})$ being a

finite dimensional subspace of polynomials

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Trace Inequalities & \mathbb{C} -ellipticity

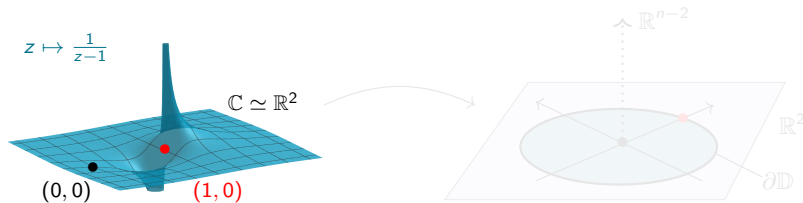
\mathbb{A} not \mathbb{C} -elliptic



\mathbb{A} contains a copy of the two-dimensional ε^D



shift singularity in $\mathbb{C} \simeq \mathbb{R}^2$ along $\{0\} \times \mathbb{R}^{n-2}$



Obtain $u \in W^{\mathbb{A},p}(\mathbb{D} \times (-1,1)^{n-2})$ with $\int_{\partial\mathbb{D}(0,1) \times (-1,1)^{n-2}} |u| d\mathcal{H}^{n-1} = +\infty$

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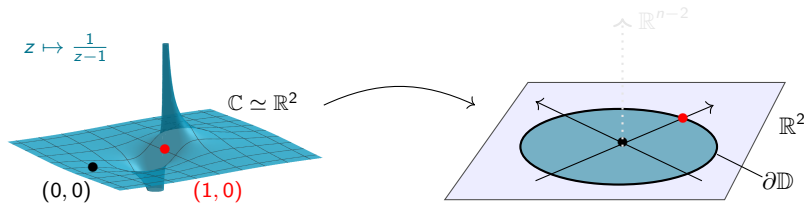
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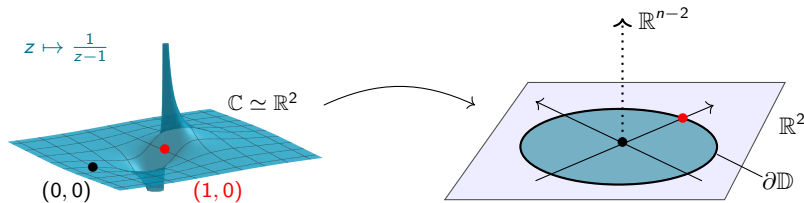
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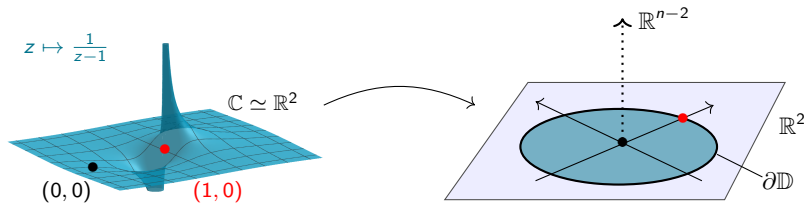
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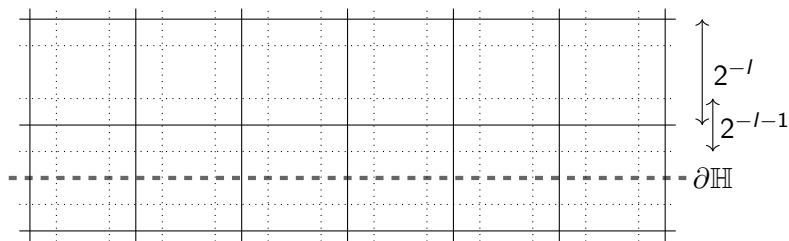


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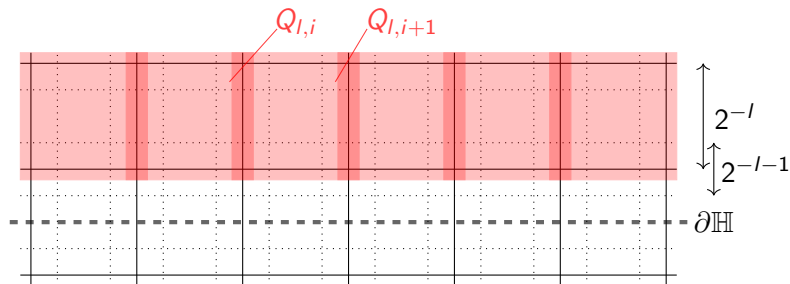


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Proof sketch for the halfspace $\mathbb{H} = \{x_n > 0\}$

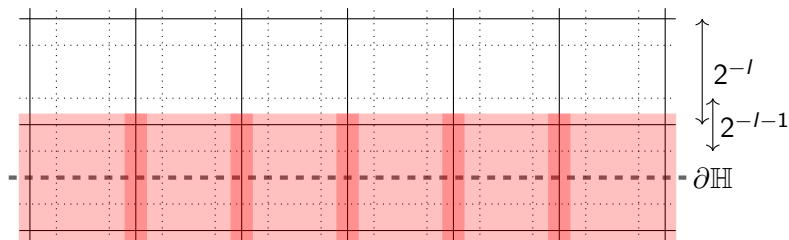


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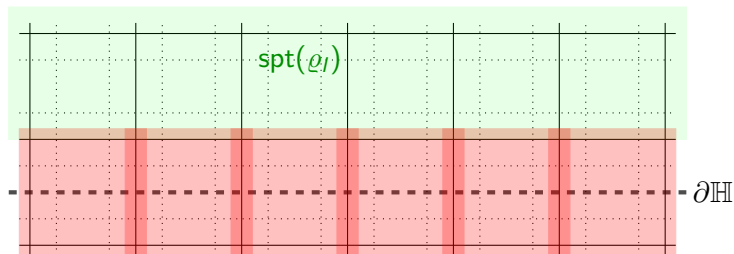
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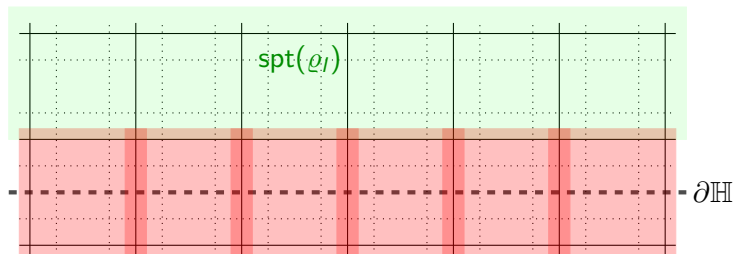


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$$T_l u := \varrho_l u + (1 - \varrho_l) \sum_{i \in \mathbb{N}} \rho_{l,i} \Pi_{l,i} u$$

- Idea: $u_j \rightarrow u$ in $W^{\mathbb{A},1}(\mathbb{H})$ und $\text{Tr}(u) = \lim_{j \rightarrow \infty} \text{Tr}(T_j u)$ in $\text{Tr}(W^{k,1})(\partial\mathbb{H})$

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Proof sketch for the halfspace $\mathbb{H} = \{x_n > 0\}$

- Use $\text{Tr}(u) = \lim_{l \rightarrow \infty} \text{Tr}(T_l u) = \sum_{l=-\infty}^{\infty} \text{Tr}(T_{l+1} u - T_l u)$
- Then

$$T_{l+1} u - T_l u = (\varrho_l - \varrho_{l+1})(\dots) + \sum_{i,m \in \mathbb{N}} \varrho_{l+1} \rho_{l,m} \rho_{l+1,i} \underbrace{(\Pi_{l+1,i} u - \Pi_{l,m} u)}_{\text{polynomials of fixed degree!}}$$

- Crucial: If $|\alpha| \leq k$,

$$\begin{aligned} \int_{Q_{l,m}} |\partial^\alpha (\Pi_{l+1,i} u - \Pi_{l,m} u)| \, dx &\lesssim \frac{1}{\ell(Q_{l,m})^{|\alpha|}} \int_{Q_{l,m}} |\Pi_{l+1,i} u - \Pi_{l,m} u| \, dx \\ &\lesssim \frac{\ell(Q_{l,m})^k}{\ell(Q_{l,m})^{|\alpha|}} \int_{\text{cubes touching } Q_{l,m}} |\mathbb{A} u| \end{aligned}$$

and for $|\beta| = k - |\alpha|$,

$$|\partial^\beta (\varrho_{l+1} \rho_{l,m} \rho_{l+1,i})| \lesssim \frac{1}{\ell(Q_{l,m})^{k-|\alpha|}} \quad \square$$

Traces and potentials

If \mathbb{A} is a first order differential operator, then in particular

- $BV^{\mathbb{A}}(\mathbb{R}^n) \hookrightarrow L^{\frac{n}{n-1}}(\mathbb{R}^n; V)$ if \mathbb{A} is \mathbb{R} -elliptic and cancelling,
- $\text{Tr}_{\mathbb{R}^{n-1} \times \{0\}} : BV^{\mathbb{A}}(\mathbb{R}^n) \hookrightarrow L^1(\mathbb{R}^{n-1} \times \{0\}; V)$ if \mathbb{A} is \mathbb{C} -elliptic.

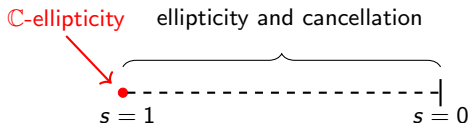
In between:

Theorem (FXG, Raita & Van Schaftingen, Indiana '21)

If $0 \leq s < 1$ and $\Sigma \subset \mathbb{R}^n$ $(n-s)$ -dimensional, then

$$\exists \text{Tr}_{\Sigma} : BV^{\mathbb{A}}(\mathbb{R}^n) \rightarrow L^{\frac{n-s}{n-1}}(\mathbb{R}^n; \mathcal{H}^{n-s} \llcorner \Sigma)$$

provided \mathbb{A} is \mathbb{R} -elliptic and cancelling ($\bigcap_{\xi \neq 0} \mathbb{A}[\xi](V) = \{0\}$).



Where we are now

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$C^{1,\alpha}$ -partial regularity of minimisers

The historical development

- **Idea:** $Q = (0, 1)^n$, $T : Q \rightarrow \mathbb{R}^{N \times n}$ and $\operatorname{curl}(T) = 0 \Rightarrow T = \nabla u$.
- We say that \mathcal{A} is an **annihilator** for \mathbb{A} , and \mathbb{A} is a **potential** for \mathcal{A} if

$$V \xrightarrow{\mathbb{A}[\xi]} W \xrightarrow{\mathcal{A}[\xi]} Z \text{ is exact for any } \xi \in \mathbb{R}^n \setminus \{0\}.$$

- Based on Dacorogna (80s), Fonseca & Müller defined

\mathcal{A} -quasiconvexity

An integrand $F : W \rightarrow \mathbb{R}$ is called \mathcal{A} -quasiconvex provided

$$F(z) \leq \int_{(0,1)^n} F(z + \psi) \, dx$$

holds for all $z \in W$, $\psi \in C^\infty(\mathbb{T}^n; W)$ with $(\psi)_{(0,1)^n} = 0$ and $\mathcal{A}\psi = 0$.

Lower semicontinuity

Call \mathcal{A} a **constant-rank operator** provided $\dim(\mathcal{A}[\xi](W))$ does not depend on $\xi \in \mathbb{R}^n \setminus \{0\}$.

Metatheorem a lá Fonseca & Müller SIAM '99, $1 < p < \infty$

If F is \mathcal{A} -quasiconvex and of p -growth, the associated integral functional

$$v \mapsto \int_{\Omega} F(v) dx$$

is weakly lower semicontinuous along sequences (v_j) with $\mathcal{A} v_j = 0$.

- Paradigm shift:

Theorem (Raita, Calc Var PDE '19)

Any constant rank operator \mathcal{A} has a potential \mathbb{A} , and then F is \mathcal{A} -QC iff

$$F(z) \leq \int_{(0,1)^n} F(z + \mathbb{A}\varphi) dx \quad \forall z \in W \forall \varphi \in C_c^\infty((0,1)^n; V).$$

- also see Arroyo-Rabasa & Simental '21: Homological approach

→ **Existence of minimisers!**

Where we are now

Function spaces, harmonic analysis
and boundary behaviour of maps



Coercivity and LSC:
 p -strong \mathcal{A} -quasiconvexity



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Partial regularity – main theorem

Theorem (Conti & FXG, '21 based on FXG, J. Math. Pures Appl. '21)

Let \mathbb{A} be an elliptic differential operator of order one and $F: W \rightarrow \mathbb{R}$ satisfy

(H1) $F \in C^2(W)$,

(H2) $|F(z)| \lesssim c(1 + |z|^p)$ for all $z \in W$ (growth bound, $1 < p < \infty$),

(H3) $F - \ell V_p$ is \mathcal{A} -QC.

Then any local minimiser of the integral functional

$$v \mapsto \int F(\mathbb{A}v) \, dx$$

is $C^{1,\alpha}$ -partially regular.

- higher order equally possible, here first order for simplicity
- Classical setting: – among others Evans, Acerbi, Fusco, Pasarelli di Napoli, Carozza, Mingione, Kristensen, Duzaar, Schmidt, Diening, Fuchs, Breit, ... and **many, many** others

Proof outline

The essential cone and span of \mathbb{A}

For a differential operator \mathbb{A} , define

$$v \otimes_{\mathbb{A}} \xi := \sum_{j=1}^n \xi_j \mathbb{A}_j v, \quad v \in V, \xi \in \mathbb{R}^n.$$

We then define the

- **essential cone** by $\mathcal{C}(\mathbb{A}) := \{v \otimes_{\mathbb{A}} \xi : v \in V, \xi \in \mathbb{R}^n\}$.
- **essential span** by $\mathcal{R}(\mathbb{A}) := \text{span}(\mathcal{C}(\mathbb{A})) \subset W$.

Upshot: If $N := \dim(V)$, then $\mathcal{R}(\mathbb{A}) \hookrightarrow \mathbb{R}^{N \times n}$.

→ upon identification, we may assume that $W = \mathcal{R}(\mathbb{A}) \subset \mathbb{R}^{N \times n}$.

For $F: W \rightarrow \mathbb{R}$ \mathcal{A} -quasiconvex, now define

$$G(z) := F(\Pi_{\mathbb{A}}(z)), \quad z \in \mathbb{R}^{N \times n},$$

with $\Pi_{\mathbb{A}}: \mathbb{R}^{N \times n} \rightarrow \mathcal{R}(\mathbb{A})$ such that $\Pi_{\mathbb{A}}[\nabla v] = \mathbb{A}v$.

The case $p \geq 2$: Properties of $G = F \circ \Pi_{\mathbb{A}}$

(H1') $G \in C^2$ if $F \in C^2$.

(H2') $|G(z)| \lesssim (1 + |z|^p)$ since F satisfies this estimate.

(H3') As a consequence of the p -strong \mathcal{A} -quasiconvexity, with $Q = (0, 1)^n$,

$$\nu \int_Q (1 + |z|^2 + |\mathbb{A}\varphi|^2)^{\frac{p-2}{2}} |\mathbb{A}\varphi|^2 dx \leq \int_Q F(z + \mathbb{A}\varphi) - F(z) dx.$$

Thus with $\phi(t) := t^2 + t^p$,

$$\begin{aligned} \int_Q |D\varphi|^2 + |D\varphi|^p dx &\lesssim \int_Q |\mathbb{A}\varphi|^2 + |\mathbb{A}\varphi|^p dx \\ &\lesssim \int_Q F(\Pi_{\mathbb{A}}(z) + \mathbb{A}\varphi) - F(\Pi_{\mathbb{A}}(z)) dx \lesssim \int_Q G(z + D\varphi) - G(z) dx \end{aligned}$$

A note on $1 < p < 2$

More intricate, hinges on Diening's shifted ϕ -functions and

$$\int_Q (1 + |z|^2 + |D\varphi|^2)^{\frac{p-2}{2}} |D\varphi|^2 dx \lesssim \int_Q \underbrace{(1 + |\Pi_{\mathbb{A}}(z)|^2 + |D\varphi|^2)^{\frac{p-2}{2}} |D\varphi|^2}_{\approx \phi_{|\Pi_{\mathbb{A}}(z)|}(D\varphi)} dx$$

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Thank you for your attention!

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